

Introduction to Parallel Computing

Distributed memory systems and programming

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Parallel Computing

Tools for MPI

- Evaluating MPI+system performance
- Monitoring execution of MPI applications (post-mortem)
- Writing own tools

Evaluating MPI+system performance

Benchmarking of individual MPI functions gives information on how a **particular** MPI library implementation performs on a **particular system**

Benchmarking is done by **special benchmarking program**, employing (hopefully) well-defined, explicit benchmarking and reporting principles. Exercise **GREAT CARE!!**

Some requirements/expectations:

- Accurate
- Reproducible
- Realistic
- Reasonably fast...

MPI support for benchmarking

- MPI_Wtime to time individual (or sequence) of MPI calls
- MPI_Barrier (careful!) or special algorithm to synchronize clocks

Repeat measurements, eliminate outliers, apply statistics, select measurement points carefully (e.g. not only powers of two message sizes)

Some well-known MPI benchmarks:

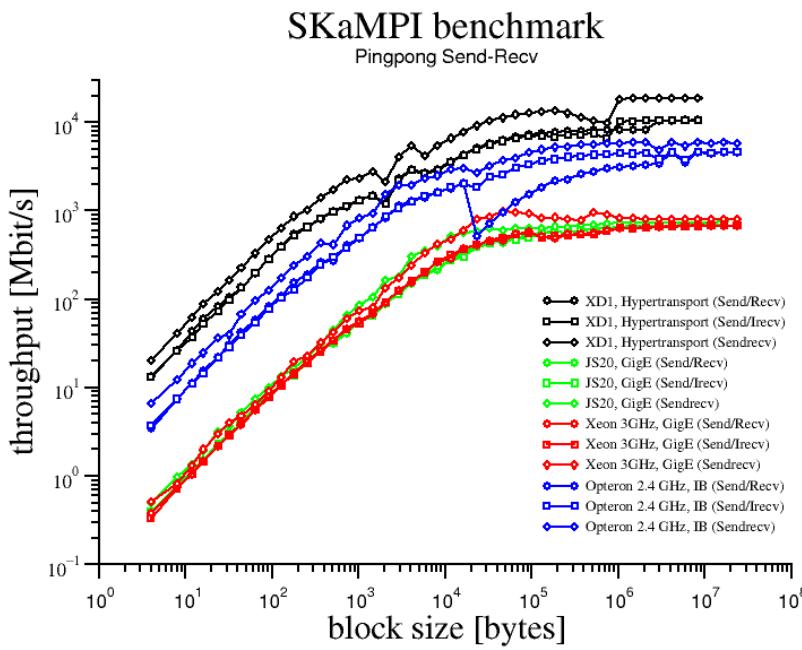
- mpptest - very basic benchmarking, delivered with MPICH
- PMB (Pallas MPI Benchmark), now IMB (Intel ...) - was **unsound**
- MPIBench
- SKaMPI
- ...

But:

No universally accepted benchmark
with broad coverage of MPI functions

Some examples with SKaMPI

Performance: communication time or bandwidth as function of message size for fixed number of processes



Rank 0

```
beg = MPI_Wtime()
MPI_Send()
MPI_Recv()
end = MPI_Wtime()
```

Rank 1

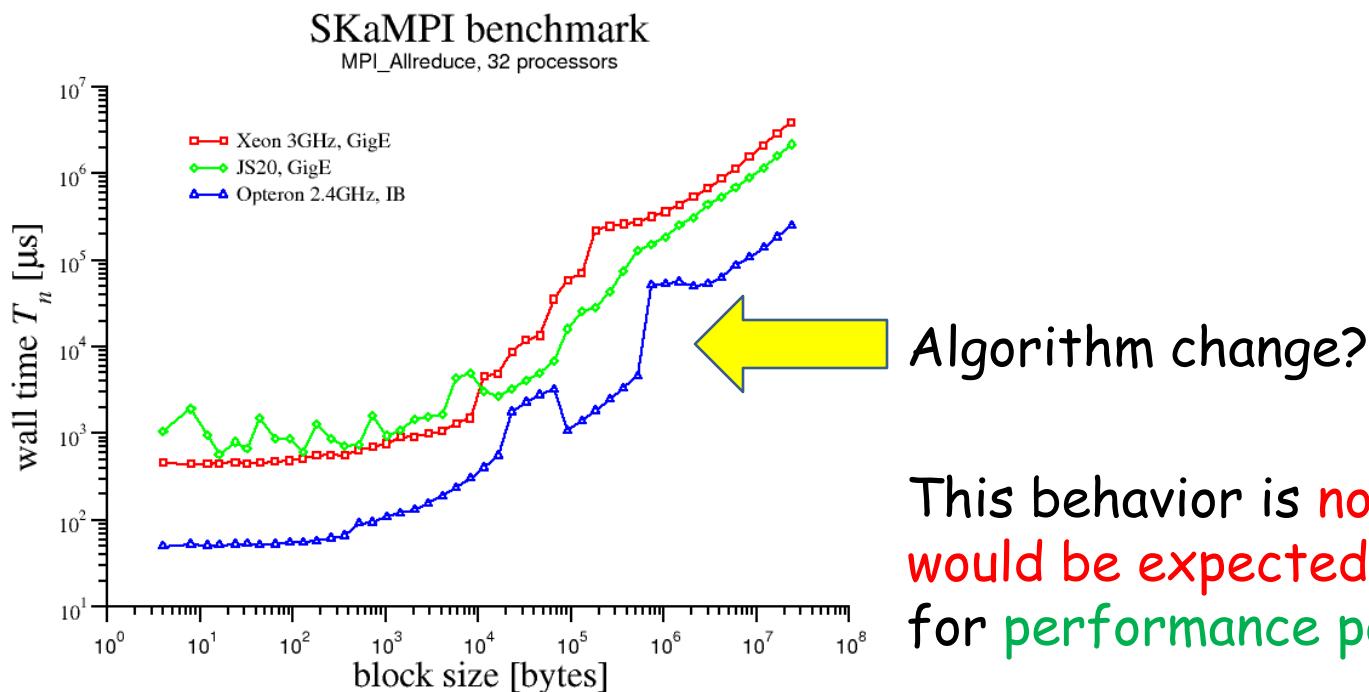
```
MPI_Recv()
MPI_Send()
```



Ping-pong test

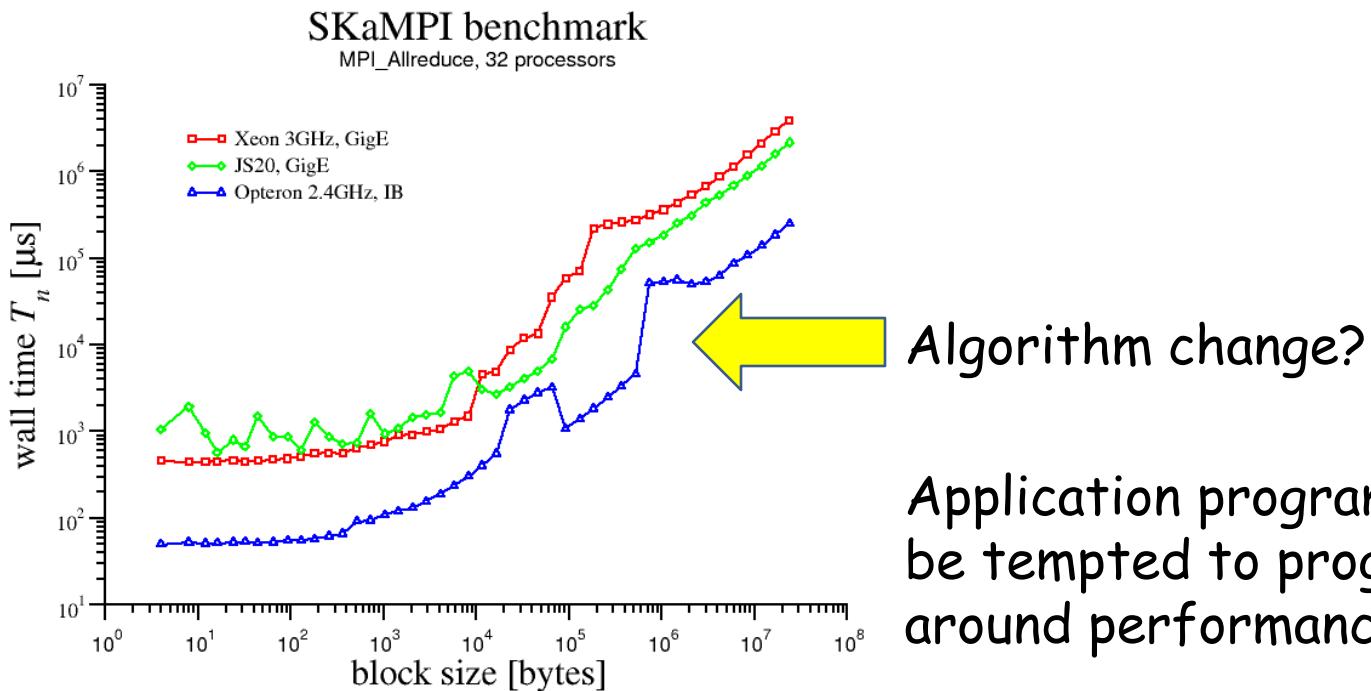
Some examples with SKaMPI

Performance: communication time or bandwidth as function of message size for fixed number of processes



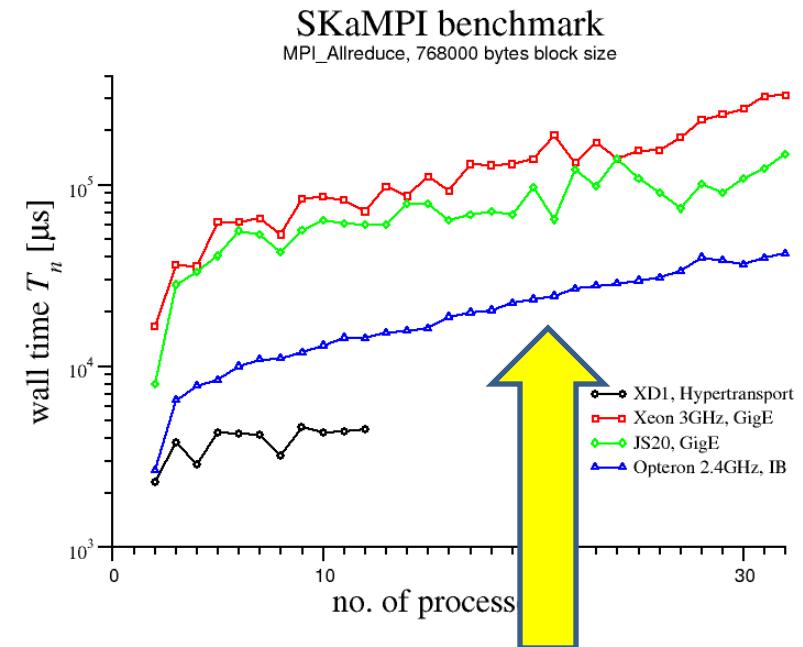
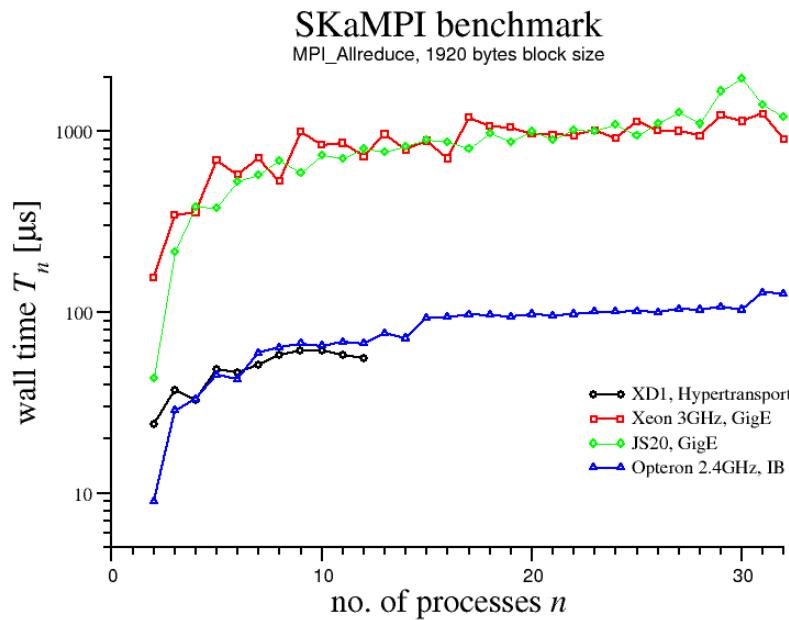
Some examples with SKaMPI

Performance: communication time or bandwidth as function of message size for fixed number of processes



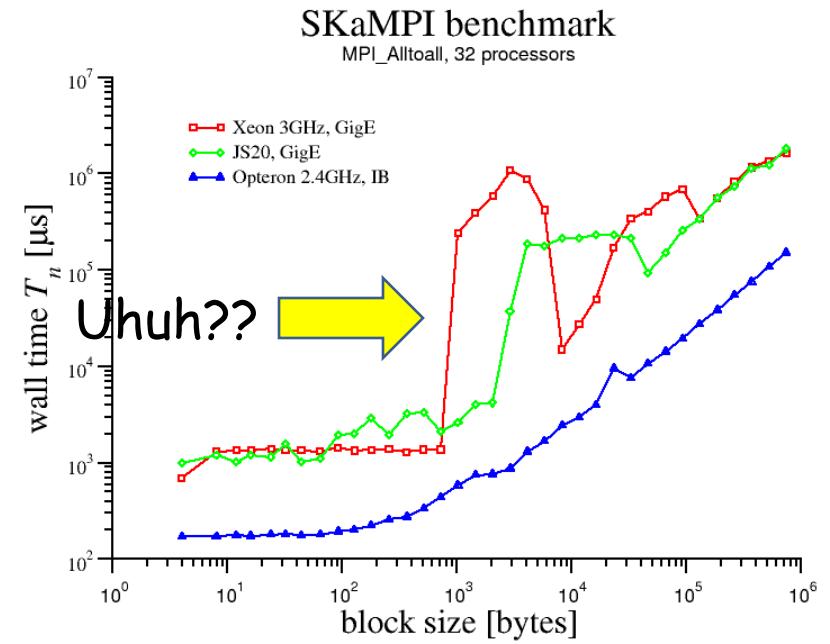
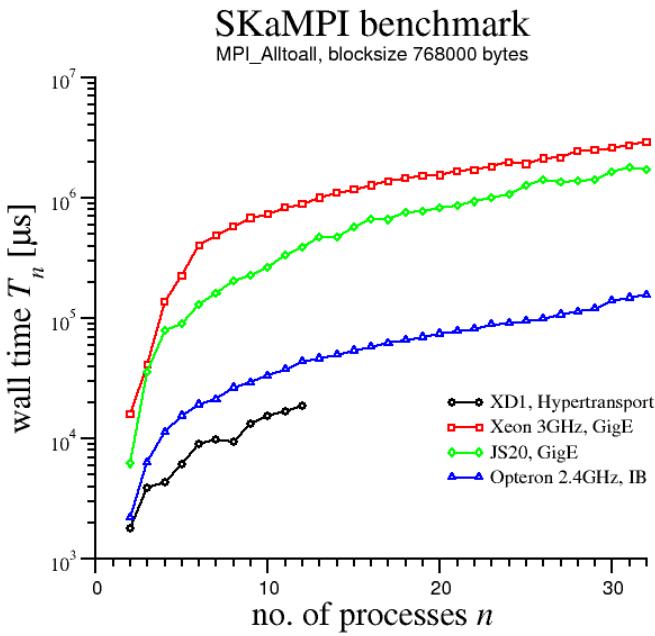
Application programmer may
be tempted to program
around performance anomaly

Scalability: communication time/bandwidth for fixed message size for varying number of processes



MPI_Allreduce should be $O(m)+o(n)$ for large data m

Performance and scalability, MPI_Alltoall



Monitoring execution of MPI applications

Basic:

how much time does the application spend in (different types of) MPI communication?

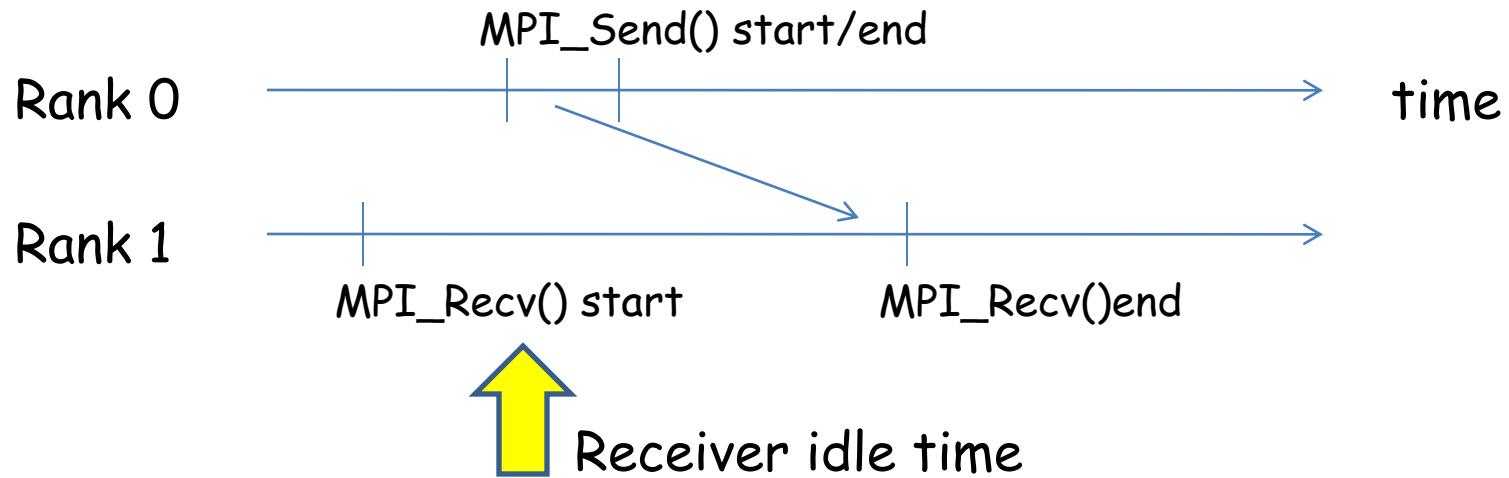
Purpose: to identify inefficiencies and load imbalances, and so-called „bottlenecks“: points where some processes wait unnecessarily for other processes due to unfortunate communication patterns

Advanced tools:

(Semi-)automatic identification of bottlenecks

Common to such tools:

- **Trace** (parts) of execution
- Post-mortem visualization and analysis of trace



Obvious problem:

scalability for large numbers of processes (visualization and trace files generation/storage/analysis)

Portable tools typically developed independently of any particular MPI implementation

How is this possible?

Basic tools:

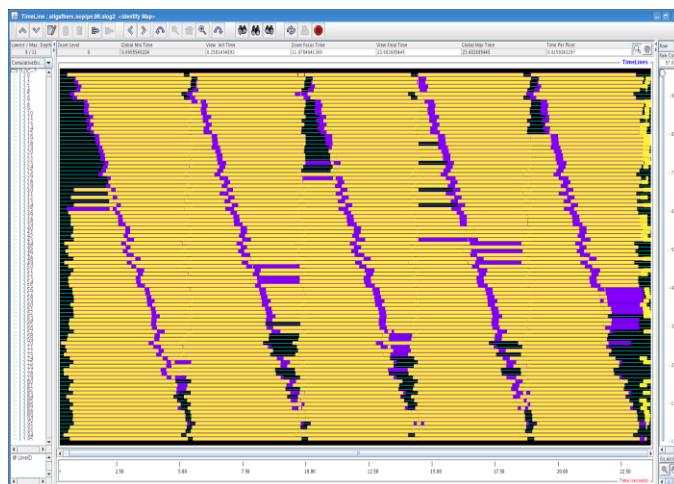
Nupshot/jumpshot developed with MPICH



Jumpshot example:
analysing two versions of an
MPI_Allgatherv algorithm

idle

comm

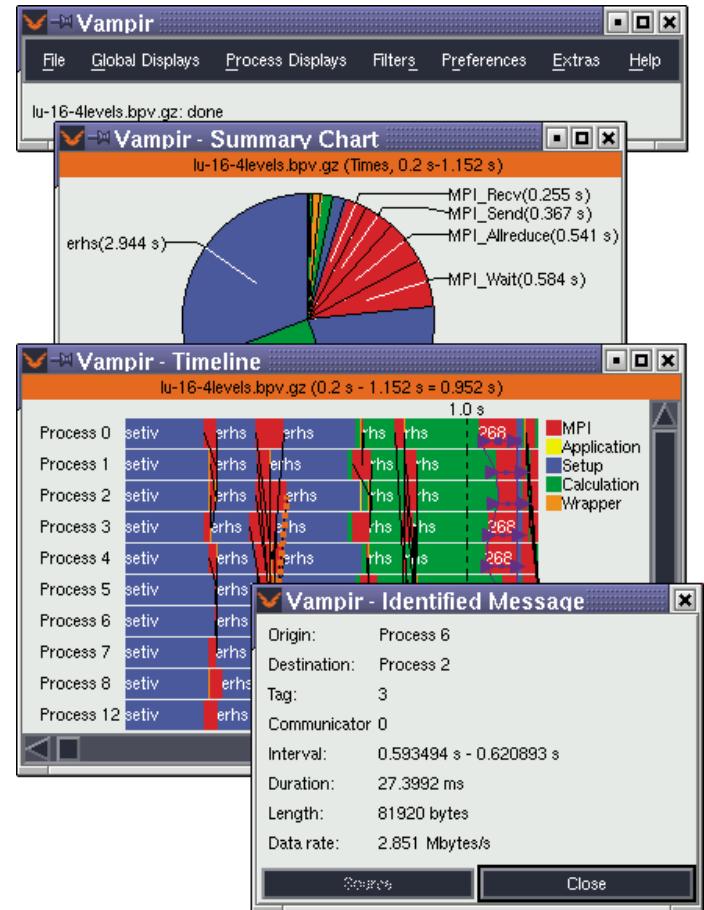


www.vampir.eu

VAMPIR (Visualization and Analysis of MPI Resources)

Advanced visualization, lots of summary information can be generated and from traces.

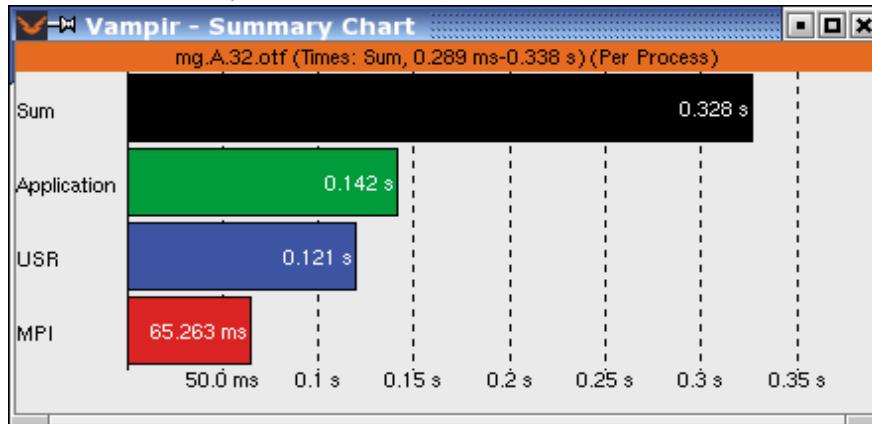
Now part of Intel tool suite



Timeline - communication behavior/process



Summary



Advanced performance tools:

- Kojak, Scalasca, Periscope
- ...

Even more advanced tools:

Suggestions for eliminating identified bottlenecks: **research topics(!)**

Performance tool development an active research area within MPI community, active groups e.g. in Germany

- Efficient, parallel analysis of very large trace files
- Handling of large trace files, compression,
- ...

MPI correctness tools

MPI implementations normally do only local, and very limited usage checking.

Wrong use of MPI functions can have **disastrous** effects:

- Application crashes
- Application deadlocks
- Application produces wrong results
- ...

directly at **wrong call**, or - **worse!** - **later**: trace/debug gives no immediate insight where the problem was

Example:

Root:

```
arguments[0] = SIZE1; arguments[1] = SIZE2;  
MPI_Bcast(arguments, 2, MPI_INT, root, comm);  
  
MPI_Scatter(data, SIZE1, ...);  
MPI_Scatter(data, SIZE2, ...);
```

Non-root:

```
MPI_Bcast(arguments, 1, MPI_INT, root, comm);  
MPI_Scatter(..., data, arguments[0], ...);  
MPI_Scatter(..., data, arguments[1], ...);
```



Big problem at
non-root

Run-time checking of correct use of MPI functions:

- Allocating and freeing MPI objects
- Pending operations correctly closed
- Correct semantics of e.g. collective operations
- ...

Some correctness tools:

- Marmot
- IMC (Intel Message Checker)
- MPI-CHECK (rudimentary tool for FORTRAN)
- NEC collectives verification interface
- ANL collectives verification interface
- ...

MPI debugging

Hard-core: `fprintf + pdbx ...`

MPI specific tools, giving access to relevant parts of MPI internals require non-standard „hooks“, and are therefore not always portable

MPI 3.0 may address this point (other project: MPI Peruse)

Example: [totalview](#) - supported by many MPICH derived MPI library implementations

Writing own tools: the MPI standard Profiling interface

Idea: for each MPI function, there is a PMPI function with same functionality. This makes it possible to any replace MPI function with own function that does additional „profiling“

Example: profiling for MPI_Send

```
MPI_Send(buffer, count, datatype, ...)  
{  
    <tool specific action>  
    PMPI_Send(buffer, count, datatype, ...);  
    <more tool specific action>  
}
```

```
MPI_Send(buffer, count, datatype, ...)  
{  
    <tool specific action>  
    PMPI_Send(buffer, count, datatype, ...);  
    <more tool specific action>  
}
```

Compile normally with mpicc into some [libmyprof.c](#)

Link application with

mpicc -lmyprof -lpmpi -lmpi ...

Special MPI function for controlling profiling interfaces

```
MPI_Pcontrol(int level, ...);
```

Typically:

level = 0: no profiling

level = 1: default level

level = 2: verbose

`MPI_Pcontrol()` allowed to take additional parameters

Example 1: collecting summary information

Amount of data communicated

- Per MPI function (or grouped: point-to-point, one-sided, collective)

- Per process/total

- Time spent in communication

```
MPI_Init(int argc, ...)  
{  
    prof_sent = 0; prof_sendtime = 0.0;  
    prof_recv = 0; prof_recvtime = 0.0;  
    <and other initialization...>  
    PMPI_Init(argc,argv);  
}
```

```
MPI_Send(buffer,count,datatype,...)  
{  
    MPI_Type_size(datatype,&typesize);  
    prof_sent += count*typesize;  
    start = PMPI_Wtime();  
    PMPI_Send(buffer,count,datatype,...);  
    prof_sendtime += (PMPI_Wtime()-start);  
}
```

For each communication operation:
Trace time spent and total data

```
MPI_Finalize()
{
    if (rank==0) {
        <gather results from all processes>
        for (i=0; i<size; i++) {
            fprintf(stderr,"Proc %i:\n");
            fprintf(stderr,"Sent %d\n",proc_sent_all[i]);
            ...
        } else {
            ...
        }
        PMPI_Finalize();
    }
}
```

Example 2:simple trace

```
MPI_Bcast(buffer,...)
{
    TRACE_event(START_BCAST, ...);
    PMPI_Bcast(buffer,...);
    TRACE_event(END_BCAST, ...);
}
```

Example 3: collective correctness tool

MPI collectives have **strict**, and sometimes **quite complex** requirements on argument consistency:

1. Collective calls must be done in same order among all processes
2. Root, operator, and similar arguments must be same for all processes
3. Data sizes must match exactly between receiving and sending processes
4. Datatype signatures must match
5. ...

Idea: create „profiling“ tool to check correct use - these checks are **too expensive for production code**

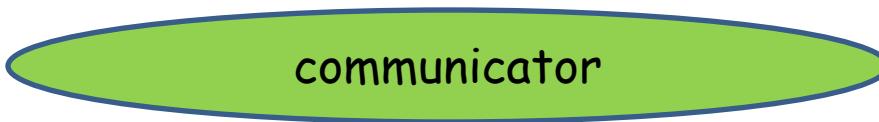


No other collective call on
communicator here

MPI_Bcast

MPI_Bcast

```
MPI_Bcast(buffer, count, datatype, root, comm) ;  
{  
    if (rank==0) {  
        calltype = BCASTTYPE; // type of collective operation  
        PMPI_Bcast(calltype, 1, MPI_INT, 0, comm);  
    } else {  
        PMPI_Bcast(calltype, 1, MPI_INT, 0, comm);  
        if (calltype!=BCASTTYPE) {  
            <ALERT: inconsistent use of collective>  
        }  
    }  
}
```



Same root argument

`MPI_Bcast(...,root,...)`

`MPI_Bcast(...,root,...)`

```
MPI_Bcast (buffer, count, datatype, root, comm) ;  
{  
    if (rank==0) {  
        rootarg = root; // set root argument  
        PMPI_Bcast (rootarg, 1, MPI_INT, 0, comm) ;  
    } else {  
        PMPI_Bcast (rootarg, 1, MPI_INT, 0, comm) ;  
        if (rootarg!=root) {  
            <ALERT: inconsistent root argument>  
        }  
    }  
}
```



Same size of buffers
Same datatype signature

`MPI_Bcast(...,root,...)`

`MPI_Bcast(...,root,...)`

Same idea, but MPI does not provide good functionality for accessing the type signature

```
MPI_Bcast(buffer, count, datatype, root, comm);  
{  
    <checking>  
    PMPI_Bcast(buffer, count, datatype, root, comm);  
    // all correct, now Bcast  
}
```

Summary

Profiling interface facility has proved useful, lots of MPI tools exist built on this functionality, easy to create own, small tools

Profiling interface **drawback**:

Only one PMPI function fallback, not possible to combine different profiling interfaces

Is being addressed in MPI Forum, new, better profiling functionality may come in MPI 3.0

Benchmarking MPI functions

Benchmarking of MPI functions

Aim:

a realistic picture of performance aspects of MPI library **and** system

Overall performance: use application (kernel), several application kernel. Know what they are doing

Specific aspects: performance of individual MPI functions

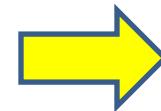
Benchmarking of MPI functions

- What is being measured?
- Reproducible (robust)
- Accurate
- Detailed, realistic picture

Basic communication
properties of library
and system

Mostly ignores interaction with other functions

```
MPI_Send(buf, count, ..., dest, ..., comm);
```



```
MPI_Recv(buf, count, ..., source, ..., comm, &status);
```

- What is being measured?
- Make assumptions clear and control them:
 1. Which functions?
 2. Point-to-point: One pair or all pairs? Process mapping (`MPI_COMM_WORLD`, `comm`)? Which data sizes? Datatypes? Where are the data (cache effects)? Data dependent (non-oblivious)?
 3. Collectives: effect of root placement, process mapping (`MPI_COMM_WORLD` vs. random `comm`). Data sizes? Datatypes? Where are the data?
 4. Other MPI functionality: ...

Pitfall: benchmarking incorrect functions

Incorrectly implemented functionality can sometimes be faster,
e.g. functionality that only works in special cases

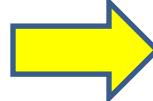
Make sure the functionality is correct, separate testing!!

- Reproducible (robust)

Individual measurements may vary: load on system (noise),
communication system itself rarely deterministic

Repeat measurement, synchronize with barrier (`MPI_barrier`)

```
for (#repetitions) : synchronize and time:
```

```
    MPI_Send(buf, count, ..., dest, ..., comm); 
```

```
    MPI_Recv(buf, count, ..., source, ..., comm, &status);
```

Pitfall: forgetting resolution of timer

```
stime = MPI_Wtime();  
MPI_<function>  
etime = MPI_Wtime();
```

Irreproducible and inaccurate results if `MPI_<function>` is fast compared to resolution of `MPI_Wtime()`. Normally `MPI_Wtime()` is good enough for communication functions

```
res = MPI_Wtick();
```

- Reproducible (robust)

Averages are **not reproducible** (outliers, system disturbance, first call may be expensive)

Repeat measurement, synchronize with barrier, use minimum

```
for (#repetitions) : time:  
    MPI_Send(buf, count, ..., dest, ..., comm); →  
        MPI_Recv(buf, count, ..., source, ..., comm, &status);
```

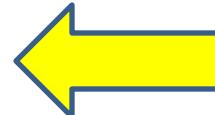
record **best measured time so far**

Pitfall: repeat correctly

```
for (#repetitions) {  
    MPI_Barrier(comm);  
    stime = MPI_Wtime();  
    MPI_Bcast(...,comm);  
    etime = MPI_Wtime();  
}
```

can be quite different from

```
MPI_Barrier(comm);  
stime = MPI_Wtime();  
for (#repetitions) {  
    MPI_Bcast(...,comm)  
}  
etime = MPI_Wtime();
```



Measures pipelining
effects

- Accurate

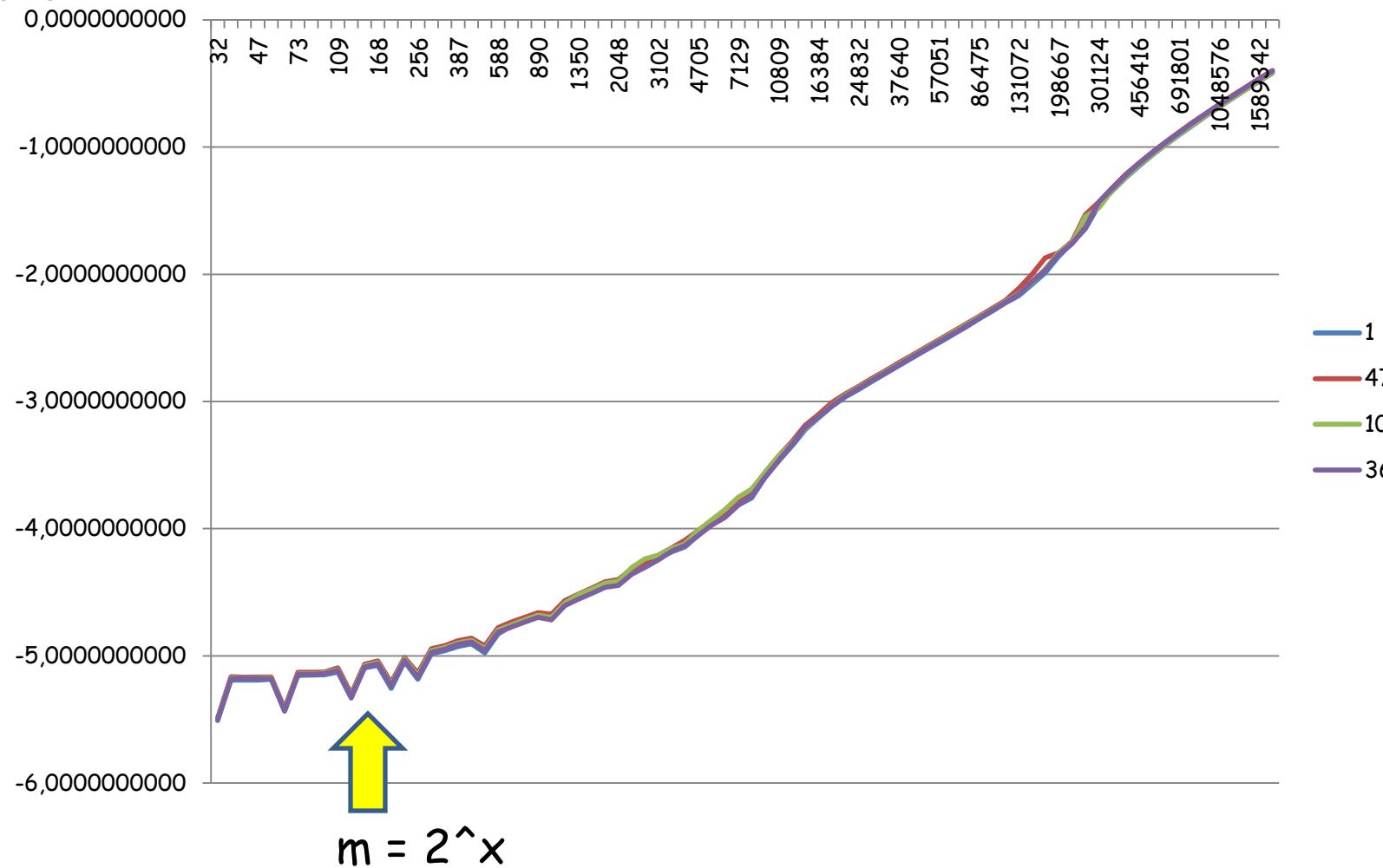
What is completion time?

- Point-to-point: ping-pong, roundtrip
- Collective: time for slowest process to complete

- Accurate

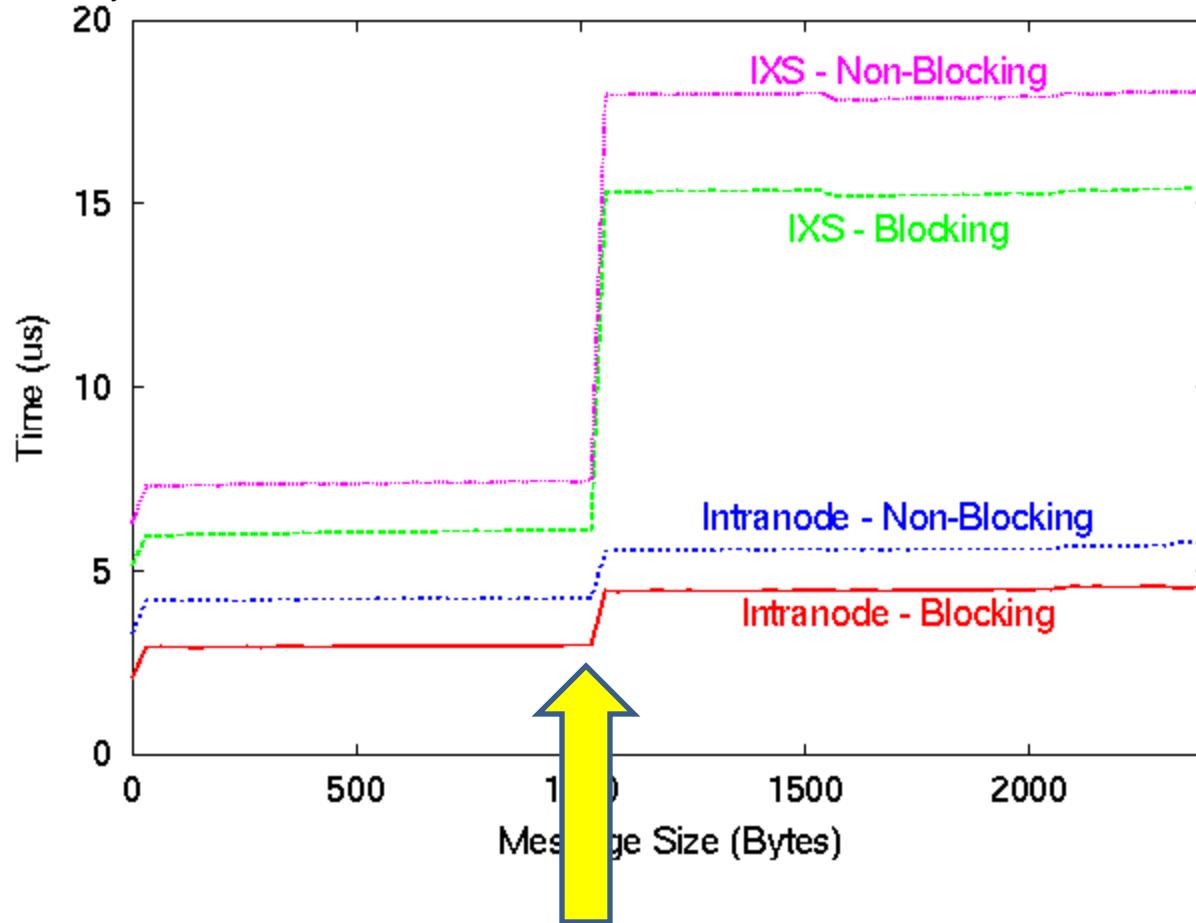
Performance as function of data size; measure points close enough; automatic refinement in critical regions

Pitfall: only powers of 2 (many MPI implementations have switch points and special cases at power-of-2 boundaries, performance might be exceptionally good or bad)



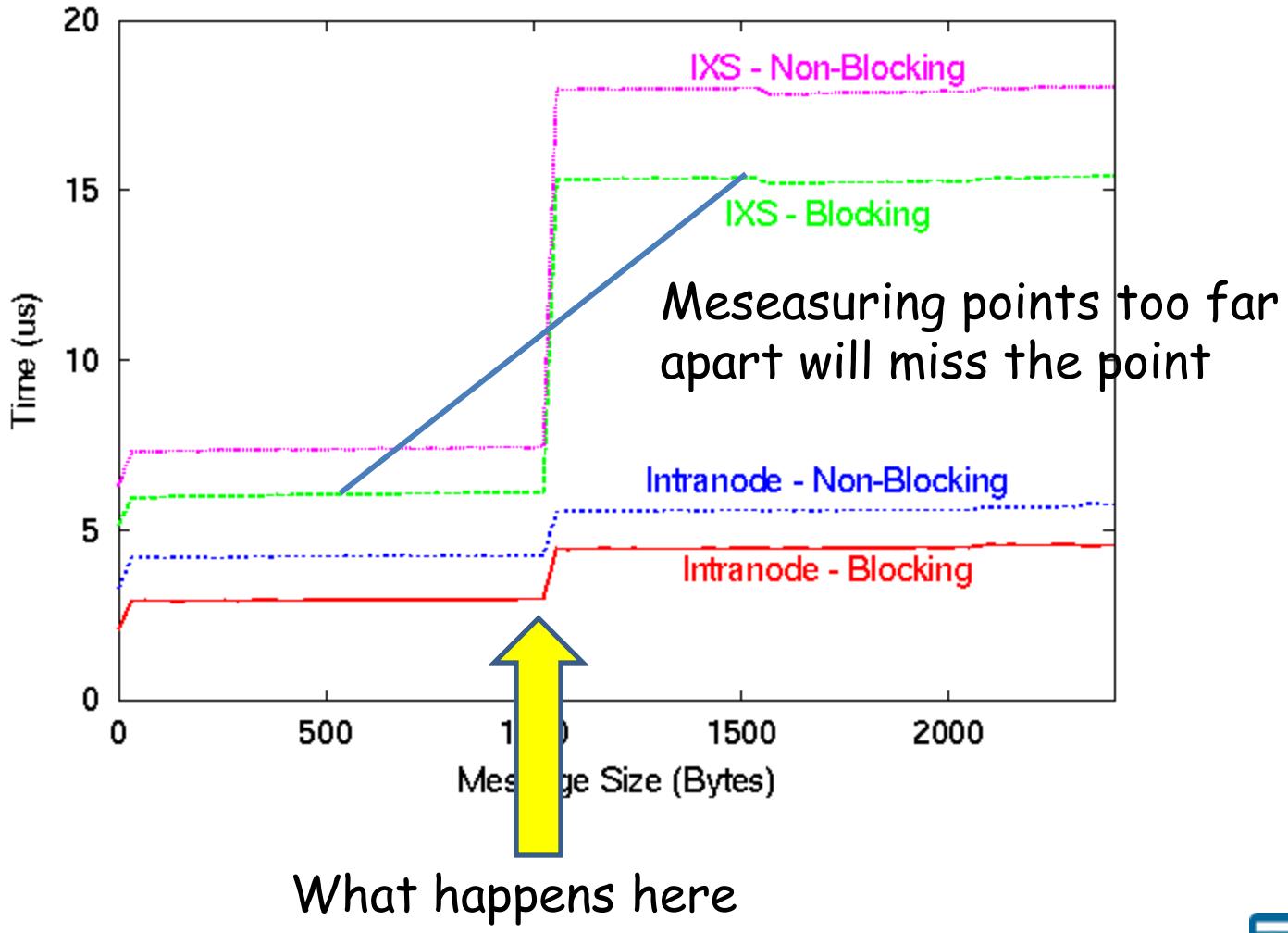
Intel SCC, measurements by Markus Pichler, January 2011

Typical point-to-point performance (mpptest of mpich2, NEC's MPI/SX)

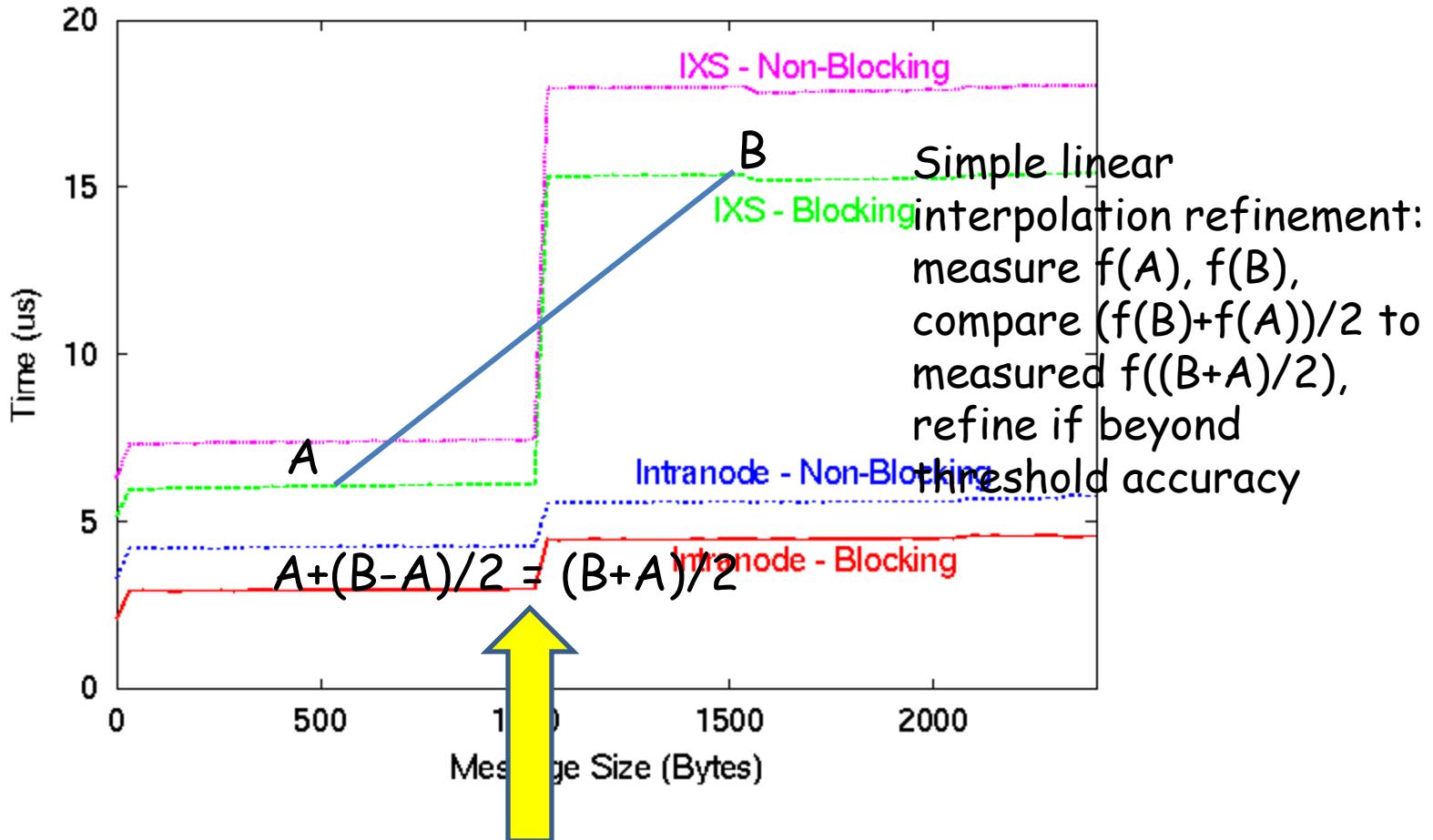


What happens here

Typical point-to-point performance (mpptest of mpich2)



Typical point-to-point performance (mpptest of mpich2)



- Detailed, realistic picture
- Data in cache or not? Process mapping (communicator).
- Point-to-point bandwidth (one pair) or bisection (all pairs)

Pitfall: using special 2-process communicator for point-to-point benchmarking

Unfair/unrealistic - has sometimes been used to demonstrate good performance...

Data structures and time for setting up and using such a communicator may be smaller than MPI_COMM_WORLD

Cache? What is accurate, realistic?

View A:

Applications compute into buffer, then communicate, so communication might well be from cache?

View B:

Applications compute many things, communicate later, communication might as well be from memory (not cached)?

From-cache communication: touch buffer before communication

Out of memory communication: use large communication buffer, step through this cyclically (see benchmark structure)

Good practice:

- Ensure correctness! (separate testing)
- Run through all counts once (without timing) to „prime“ system
- Use repetitions, measure minimum
- Many counts, not only powers of 2, powers of 10
- Automatic refinement (if possible)
- Provide for different communicators
- Point-to-point: provide for one pair/all pairs
- Provide for different datatypes
- Control cache-behavior if possible

Suggested benchmark structure, precomputed counts

```
for (#repetitions) {
    for (i=0; i<counts; i++) { // step through all counts
        MPI_Barrier()
        stime = MPI_Wtime()
        MPI_<function>(buffer); // in or not in cache?
        etime = MPI_Wtime();
        time[i] = etime-stime; // local time
        totaltime[i] += time[i]; // add to total
    }
    // find slowest process
    MPI_Reduce(time,counts,MPI_DOUBLE,MPI_MAX,0,comm);
    if (rank==root) {
        for (i=0; i<counts; i++) {
            if (time[i]<besttime[i]) besttime[i] = time[i];
            // best of slowest for all counts
        }
    }
}
```

„Best possible time of last process to finish“
WS11/12 ©Jesper Larsson Träff

This gets more complicated if refinement is employed (the number of measurement points can vary over the repetitions)

Statistical question:

How many repetitions needed to get a stable "best of slowest" value?

Experience: 20-100 iterations suffice

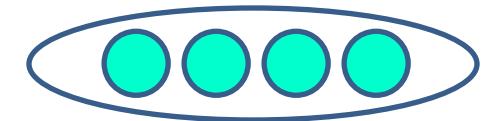
MPI_<function> for unidirectional bisection BW measurement:

```
if (rank%2==0&&rank<size-1) {  
    MPI_Send(sendbuf,c,type,rank+1,0,comm);  
    MPI_Recv(recvbuf,c,type,rank+1,0,comm,  
             MPI_STATUS_IGNORE);  
} else if (rank%2==1) {  
    MPI_Recv(recvbuf,c,type,rank-1,0,comm,  
             MPI_STATUS_IGNORE);  
    MPI_Send(sendbuf,c,type,rank-1,0,comm);  
} else {  
    MPI_Sendrecv(sendbuf,c,type,rank,0,  
                recvbuf,c,type,rank,0,comm,  
                MPI_STATUS_IGNORE);  
}
```

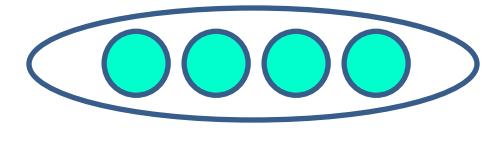
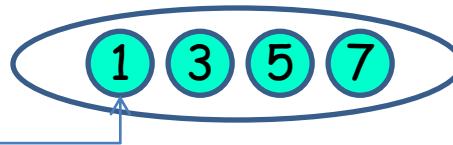
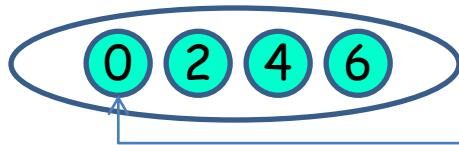
MPI_<function> for bidirectional bisection BW measurement:

```
if (rank%2==0&&rank<size-1) {  
    MPI_Sendrecv(sendbuf,c,type,rank+1,0,  
                recvbuf,c,type,rank+1,0,comm,  
                MPI_STATUS_IGNORE);  
} else if (rank%2==1) {  
    MPI_Sendrecv(sendbuf,c,type,rank-1,0,  
                recvbuf,c,type,rank-1,0,comm,  
                MPI_STATUS_IGNORE);  
} else {  
    MPI_Sendrecv(sendbuf,c,type,rank,0,  
                recvbuf,c,type,rank,0,comm,  
                MPI_STATUS_IGNORE);  
}
```

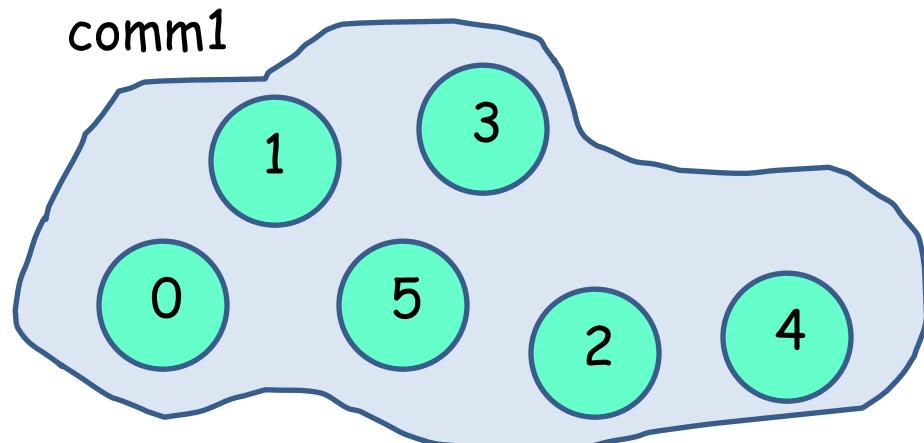
SMP system communication performance



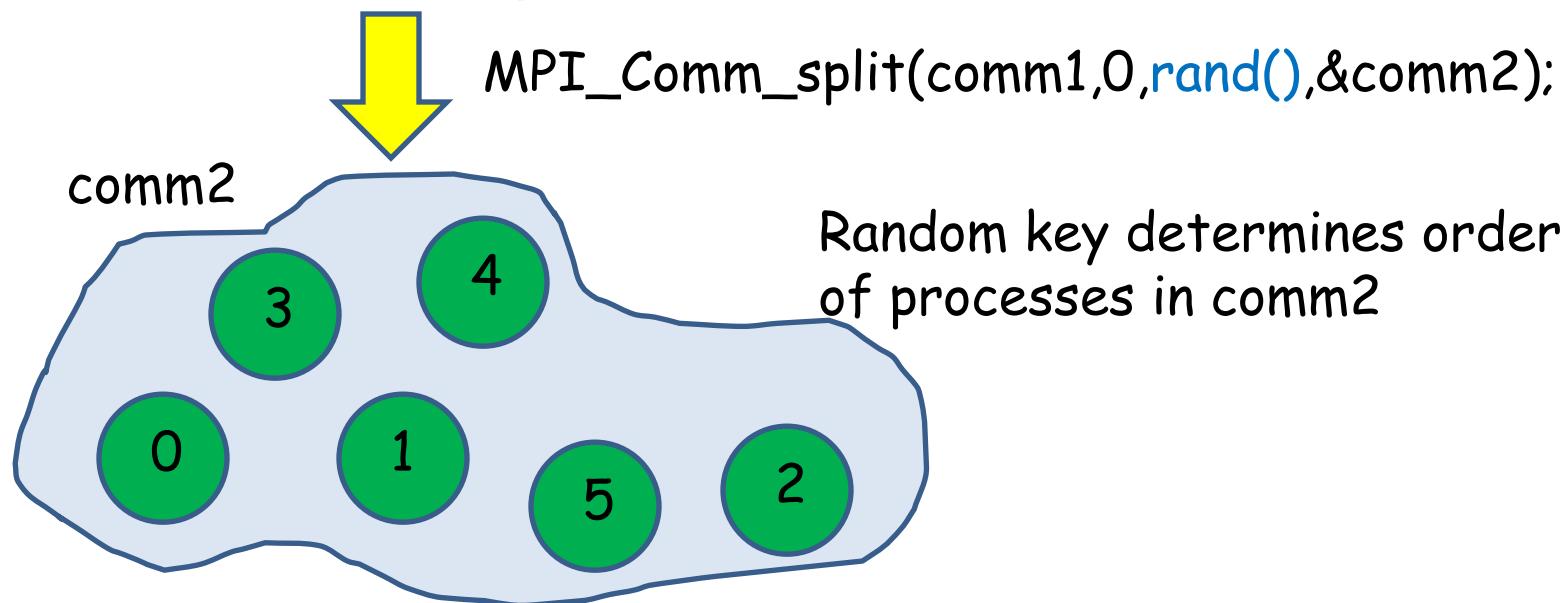
versus?



„nodes“ with „fast“ (shared memory) communication,
interconnected with „slower“ (1-ported) network



„Random“
communicator:
Random association of
processes to
processors



Random key determines order
of processes in comm2